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In the basis of microscopic level we categorize solids into 3 main types.

Tab force lagate hein tou solids mein deformation aati he.

Crystalline Solids

→ Specific arrangement of Particles



→ Anisotropy

Polycrystalline Solids

→ Solid material made up of many small crystals of random direction is called polycrystalline solid



Amorphous Solids

→ Solid materials, whose constituent particles are arranged in a random manner are called amorphous solids.

Isotropy

A material having uniform and identical properties in all directions. The solid basically have regular and arranged pattern.

Anisotropy

Opp to isotropy

X-ray diffraction and Bragg's Law



Unit cell :-

- A single cell
- combining unit cell makes crystal
- like a brick and Building
- Building Block of a crystal

X-ray diffraction and Bragg's Law is actually a technique used to determine the shape of crystal lattice.

Lattice

An imaginary geometrical framework to join basis is called Lattice.

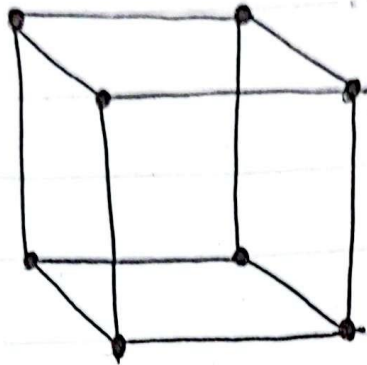
Crystal lattice - The structure of a crystal obtained by the repetition of the unit cell is called crystal lattice.

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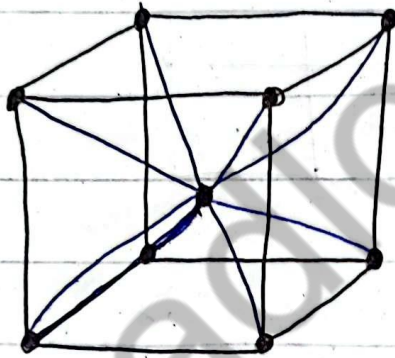
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Simple Cubic



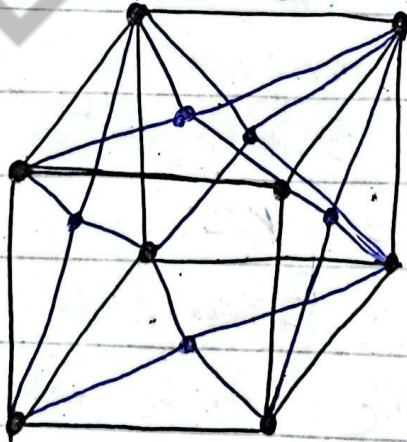
(SC)

Base Centred Cubic



(BCC)

Face Centred Cubic



(FCC)

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7.2 DEFORMATION IN Solids

16-Oct-2024

The Change in Shape length or volume of a solid, when it is subjected to an external force, is called deformation

Stress

• force acting per unit area

• In case of Stress & Pressure angle between force & Area is 90°

• Only in Solids

• When a force acts on an area, Perpendicularly, then, it is called as Stress.

$$\text{Stress } (\sigma) = \frac{F}{A} = \frac{N}{m^2} = Nm^{-2}$$

• Area zyada impact kam
impact zyada Area kam

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of One Dimensional (length) (m)

The one dimensional stretching force acting on the area ~~and~~ of cross-section of a body, which produces linear deformation, then it is called tensile stress.

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of Two Dimensional (Area) (m^2)

The two dimensional stretching force acting on the area of cross sectional of a body, which produces linear deformation, then it is called shear stress

of Three Dimensional (volume) (m^3)

The three dimensional stretching force acting on the volume of a body, which produces linear deformation, then it is called volume strain

MODULE'S OF ELASTICITY

YOUNG'S MODULES :-

It is object per force to gain our us ki length mein change si, Tou us case ka constant young's modulus he.

As stress is given by:-

$$\text{Stress} = \frac{F}{A} \quad \text{--- i}$$

Tensile strain

$$\Rightarrow \Delta L = L' - L \quad \text{--- ii} \quad \text{T-strain} = \Delta L / L \quad \text{--- iii}$$

Since, the young's modulus-

$$\Rightarrow \text{Young's Modulus} = \frac{\text{stress}}{\text{strain}}$$

$$\Rightarrow \text{Young Modulus} = \frac{F/A}{\Delta L/L}$$

$$= \frac{F}{A} \cdot \frac{L}{\Delta L}$$

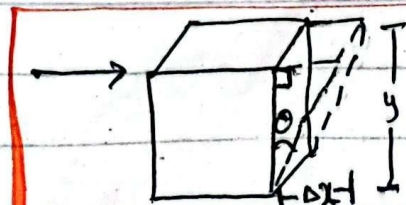
$$= \frac{FL}{A\Delta L}$$

So, its unit is N/m^2

Shear Modulus :-

Since, $\tan(\theta) = \frac{\Delta x}{y}$ --- i

Shear Strain $\rightarrow \frac{\Delta x}{y}$



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here eq (i) shows shear strain.

$$\text{Stress} = \frac{F}{A}$$

$$\text{Shear Modules} = \frac{\text{Shear Stress}}{\text{Shear Strain}}$$

$$= \frac{F/A}{\Delta x / y} \quad \left| \begin{array}{l} \text{(OR)} \quad \frac{F/A}{\tan \theta} \approx \frac{F/A}{\theta} \\ \tan \theta \approx \theta \\ \approx \frac{F}{A\theta} \end{array} \right.$$

BULK MODULES

$$\text{Bulk Strain} = -\frac{\Delta V}{V}$$

$$\text{Bulk Stress} = \frac{F}{A}$$

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$$\text{Bulk Modules} = \frac{FV}{-A\Delta V}$$

"HOOK'S LAW"

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Stress \propto Strain
 [Under the Elastic Limit]

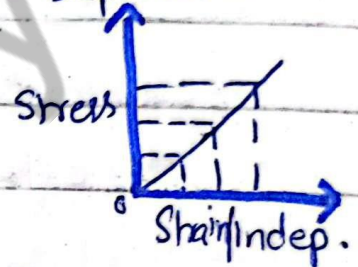
Stress = constant \times strain

$k = \frac{\text{Stress}}{\text{Strain}}$

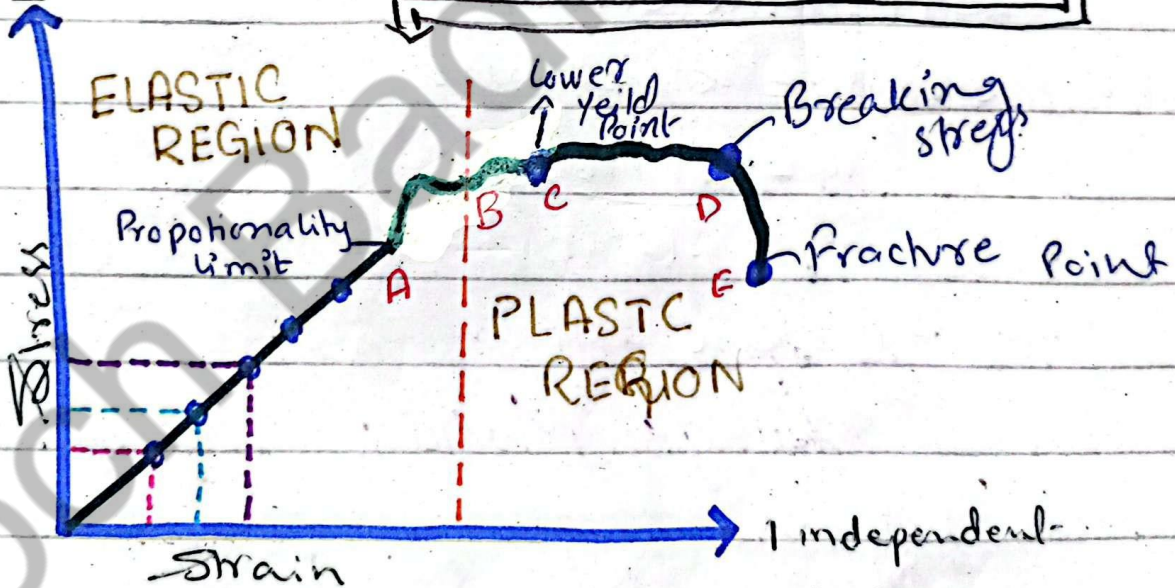
as, Slope = $\frac{\text{Rise}}{\text{Run}}$

Slope = $\frac{\Delta y}{\Delta x}$

Graphically dependent



dependent



Q Point ABCDE short ya overall 1 long

Elastic Potential Energy

Q Which one of the following has more elastic Potential Energy?

a - Steel ✓ b - rubber band c - none

→ stress to strain ratio steel ka zyada hai

→ More Dheer Substance = More E.P.E.

Modules of Metallic Wire

Stress \propto Strain

$$\text{stress} = k \times \text{strain}$$

$$k = \frac{\text{Stress}}{\text{Strain}}$$

$$\text{Stress} - \frac{F}{A} = \frac{k \cdot x}{L} - \text{Strain}$$

Young's Modules

$$\text{Young's Modules} = \frac{\text{Force}}{\text{Area}} \times \frac{\text{Length}}{\Delta \text{Length}}$$

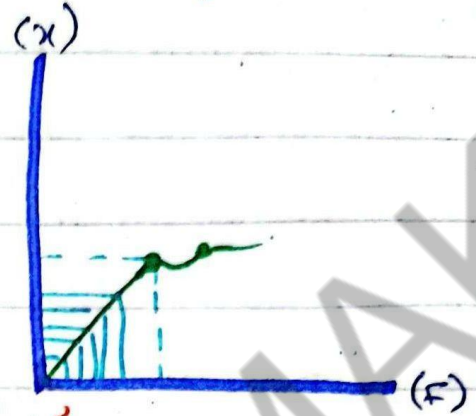
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Work from Force extension graph

F	10	20	30	40	50
x	5	10	15	20	25
$K = \frac{F}{x}$	2	2	2	2	2



$$\text{Area of } (Fx) = F_{\text{avg}} \times x \quad \text{--- i}$$

$$F_{\text{avg}} = \frac{F_1 + F_2}{2} = \frac{0 + F}{2} = \frac{F}{2}$$

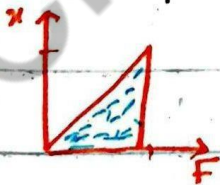
$$F_{\text{avg}} = F/2 \quad \text{--- ii}$$

Putting ii in i

$$\begin{aligned} \text{Area of } (Fx) &= F_{\text{avg}} \times x \\ \text{work} &= \frac{F}{2} \times x \end{aligned}$$

$$\text{work} = \frac{1}{2} Fx \quad \text{--- iii}$$

Make Special Tip :-



$$\begin{aligned} \text{Area of } \Delta &= \frac{1}{2} \times \text{Base} \times \text{height} \\ \text{work} &= \frac{1}{2} \times F \times x \end{aligned}$$

Q Value of F n x will be given and we hv to Prove the formula

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Elastic Potential Energy

Since, Work energy theorem:-

Elastic Potential Energy = Work done

Since from Hooke's law

$$F = kx \quad \text{--- iv}$$

As, work = $\int F dx$ --- v

Putting eq. i in iv, then,

$$W = \frac{1}{2} \times (kx) x$$

$$W = \frac{1}{2} kx^2$$

$$P.E_{(elastic)} = \frac{1}{2} kx^2 \quad \text{--- vi}$$

On the Basis of work done

$$W_{work} = P.E_{(elastic)} = \frac{1}{2} Fx \quad \text{--- vii}$$

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$$\text{as, } \gamma = \frac{F/A}{x/L}$$

$$F = \gamma \times \frac{x}{L} \times A \quad \text{--- viii}$$

Putting viii in vii

$$P.E_{(elastic)} = \frac{1}{2} \left(\frac{\gamma A}{L} \right) x^2 \quad \text{--- ix}$$

On the Basis of Young's modulus