

Chapter no: 1 Simple Harmonic motion and waves.

SHM,
 def: $a \propto -x$. A body has SHM if its F is \propto to x from mean position and always directed towards mean position.
 $-ve$ sign indicates motion towards mean position.

- 3 examples:
 • mass-spring system
 • simple pendulum
 • ball & bowl system
1. Mean position (normal point) = 0.
 2. Extreme positions (A, B).

mean position, $P.E = mgh, mg0 = 0$.
 $P.E = 0 / \text{min}$.
 Extreme position: (A, B).
 $v = \text{min}, k.E = \text{min}, h/x = \text{max}$.

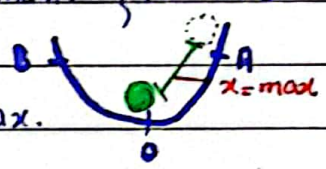
Main Points:

① **Energies:** kinetic (K.E), Potential (P.E).
 • mean position: $v = \text{max}, k.E = \frac{1}{2}mv^2 = \text{max}$.
 So, $k.E = \text{max}$, whereas, $h/x = 0$ at

mean position:
 $k.E = \text{max}$
 $P.E = \text{min}$
 Extreme position:
 $k.E = \text{min}$
 $P.E = \text{max}$.

Gain in $k.E = \text{Loss in } P.E$.

② **Acceleration:** \vec{a} ; $a \propto -x$, Net force & acceleration
 mean position: $x = \text{minimum}$.
 So, $a = \text{min}$.
 extreme position: $x = \text{max}$.
 So, $a = \text{max}$.

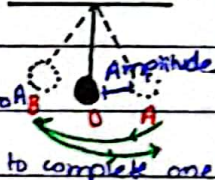


velocity and acceleration are opposite.
 (mean): $v \downarrow, a \uparrow$ - extreme: $v \uparrow, a \downarrow$

③ **Velocity:** (v)
 mean position: due to restoring force the body quickly passes the extreme position, So $v = \text{max}$ at mean position.
 and extreme position = body stops for a nano sec
 we consider v velocity to be zero
 So, at extreme $v = \text{min}/0$.

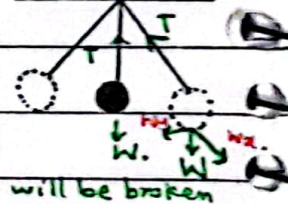
Some important definitions:

Vibration: one complete round trip: A to B and back to A.
 i.e. "one complete round trip".
Time period: Time required to complete one vibration.
Frequency: No. of vibration / time $f = \frac{1}{T}$.
Amplitude, displacement: Time taken (t), Any time, no restrictions.
Time period (T): Time in which body complete one vibration. (restriction).



⇒ Simple pendulum imp point

Forces:
 $W_y = mg \sin \theta$
 $W_x = mg \cos \theta$
 Weight (w) will be broken down in x, y components.



Time period & frequency: Time period of simple pendulum.
 $T = 2\pi \sqrt{\frac{m}{k}}$ but $f = \frac{1}{T}$ So, $f = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$

Damped oscillation: Due to some frictional or resistive force, a body will do damped oscillation. i.e. the amplitude will decrease with time.

Applications: shock absorber is used in cars, in order to prevent damages to car while moving on bumpy roads.

working: (summarized): When shock is given due to bumpy roads, the Shock Absorber will compress and oil will come out of pores slowly through the pores. The oil will slowly decrease the amplitude of the shock. Temperature of the oil increases. The impact of force reduces and drive is comfortable.



$W = F$ (F_x, F_y); (W_x, W_y):
 $W_x = W \cos \theta = mg \cos \theta$.
 $W_y = W \sin \theta = mg \sin \theta$.
 $W = mg$.
 $F_{\text{restoring}} = mg \sin \theta = W_y$.
 $T = mg \cos \theta = W_x$.

1. Tension will be balanced by W_x .
2. W_y will help pendulum move back and forth.

Wave.

Date:

Sun Mon Tue Wed Thu Fri Sat

"disturbance in the medium which causes the particles of the medium to undergo oscillatory motion about their mean position in equal intervals of time."

Types: Mechanical & electromagnetic.

Difference between mechanical and electromagnetic waves:

Mechanical	Electromagnetic
Definition: waves that require medium for their propagation.	Definition: waves that do not require medium.
medium: medium is needed.	medium: medium not required.
Example: water, sound waves.	Example: x-ray, heat waves.

Relation b/w v, f, λ .

velocity = $\frac{d}{t}$

$T = \frac{1}{f}$

$d = \lambda$

So, $v = \frac{\lambda}{t}$

$v = f\lambda$

"waves donot transfer matter. they transfer energy."

Difference b/w Types of Mechanical waves.

Ripple Tank;

LONGITUDINAL.

Def:

The particles of medium move back and forth along the direction of propagation of wave.

Production of wave: Longitudinal waves can be produced on a spring (slinky). fix one end & hold the other. now move it back & forth. it push it and pull it.

move faster in solids than gas or liquid.

compression & rarefaction.

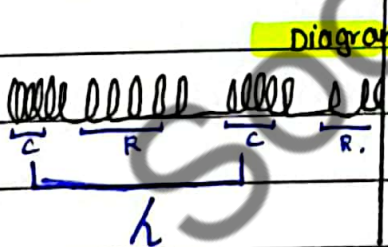
Parts of waves: compression; loops of spring are close together.

Rarefaction: loops are spaced apart.

⇒ the compression & rarefaction move back and forth along direction of motion of wave.

wave length:

The distance b/w two consecutive compressions is wavelength.



TRASVERSE.

The vibratory motion of particles of medium is perpendicular to direction of propagation of wave.

Here we need slinky too, fix one end, hold the other, move the slinky or spring up & down. A wave in the form of crest & trough will move toward fix point.

Transverse move through solids at a speed of less than half of speed of longitudinal waves.

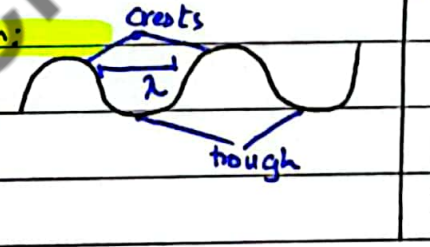
Crest and Trough.

Parts of waves: crest: highest points

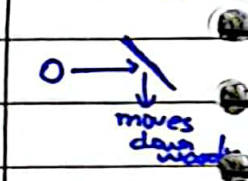
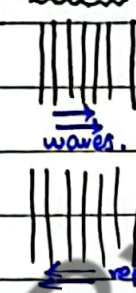
trough: lowest points of wave.

wave length:

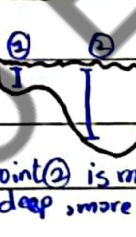
The distance b/w two consecutive crests or trough is wavelength.



Reflection:



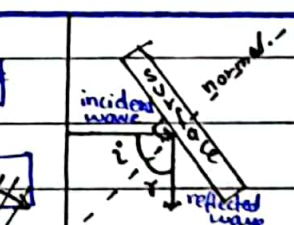
Depth:



Imp points: Speed of No. of particles. more depth = more no. of particles. So depth \propto speed $\lambda \propto v$.

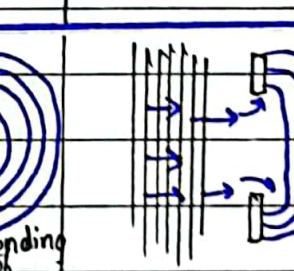
shallow Deep water. speed $\propto \lambda$ changes when as frequency remains unchanged.

Refraction:



normal is just a \perp line that passes through surface and forms 90° angle. $\angle i = \angle r$.

Diffracting:



• small opening more bending of waves
• big opening/ gap less bending of waves.

2. Conditions:

- ① lambda should be greater than length ($\lambda > L$).
- ② lambda should be equal to length ($\lambda = L$).