

Date: _____

Formula Sheet

Day: _____

Unit no:-2 Vectors & Equilibrium

Key points
Resultant of 2 vectors max if direction is same. will be min. if direction is opposite.

Geometric vectors:- Without reference to coordinate axes.

Algebraic vectors:- With reference to coordinate axes.

Unit vectors:- Only used to tell direction magnitude (±).

$\hat{i}, \hat{j}, \hat{k}$ for x, y, z

$$\hat{A} = \frac{\vec{A}}{|\vec{A}|}$$

In plane (2D) only 1 angle is required to represent a vector while 3 angles are required to represent a vector in space.

Points -
Resolution of vector is reverse process of addition of vector.

Two like parallel vectors of equal magnitude are called equal vectors.

Commutative law of vector addition:- $\vec{A} + \vec{B} = \vec{B} + \vec{A}$

Subtraction of vectors:- $\vec{A} - \vec{B} = \vec{A} + (-\vec{B})$

Multiplication of vector with a scalar:- (Cases)

- If $k=0$ then $k\vec{A} = \vec{0}$ (null) vector
- If $k > 0$ then $+k\vec{A} = k\vec{A}$ (Only Magnitude changes)
- If $k < 0$ then $-k\vec{A} = -k\vec{A}$ (Both magnitude & direction changes)

If \vec{A} & \vec{B} are 2 vectors then magnitude of their resultant is.

Determination of vector by rectangular components:-

$A = \sqrt{A_x^2 + A_y^2}$ (Magnitude) $\theta = \tan^{-1}(A_y/A_x)$ (Direction)

$R = \frac{A^2 + B^2 + 2AB \cos \theta}{\cos \theta}$
 $\theta = 0^\circ (A+B)$
 $\theta = 180^\circ (A-B)$
 $\theta = 90^\circ (\sqrt{A^2 + B^2})$

Vector addition by rectangular components:-

$R = \sqrt{(A_x + B_x)^2 + (A_y + B_y)^2}$ (Magnitude)
 $\theta = \tan^{-1}\left(\frac{R_y}{R_x}\right)$ (Direction)

	II		I
x'	$R_x = -$		$R_x = +$
	$R_y = +$		$R_y = +$
	$\theta_R = 180^\circ - \phi$		$\theta_R = \phi$
	III		IV
	$R_x = -$		$R_x = +$
	$R_y = -$		$R_y = -$
	$\theta_R = 180^\circ + \phi$		$\theta_R = 360^\circ - \phi$

Torque plays same role in angular motion as force plays in linear motion.

Torque:- Product of Force & position vector

- $\vec{\tau} = r \times F \sin \theta \hat{n}$ Maximum $90^\circ, 270^\circ$
- SI unit Nm Minimum $0^\circ, 180^\circ$
- Dimension $[ML^2T^{-2}]$ (Positive torque)
- Vector quantity. (Negative)

Direction:- By right hand rule (Anti-clockwise)

Dependence:-
 - Magnitude of force (Clockwise)
 - Magnitude of position vector.
 - Angle between force vector & position vector.

Used to determine angular acceleration

$\tau = I\alpha$

Equilibrium:- If a body has no acceleration,

then it is said to be in equilibrium.

Complete equilibrium
 A body will be in complete equilibrium if both conditions are satisfied (static equilibrium).

1st Condition $\sum \vec{F} = 0$ Books lying on table Parasutrooper	2nd Condition $\sum \vec{\tau} = 0$ Seesaw Meter rod balanced on wedge
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Scalar product **vector product**

If $\theta = 0^\circ$ (parallel) Maximum AB	Minimum 0
If $\theta = 90^\circ$ (Perpendicular) Minimum 0	Maximum AB
If $\theta = 180^\circ$ (Antiparallel) -ive maximum $-AB$	minimum 0
Self product Maximum A^2	Minimum 0
Other name Dot product	Cross product
Trigonometric ratio $\cos \theta$	$\sin \theta$
For direction in vector product we use the right hand rule ☺ vector product gives area of parallelogram.	