


Unit no: 05 Rotational and Circular motion

Angular velocity
vector quantity
[T⁻¹]
SI unit rad/s
Angular acceleration
vector quantity
[T⁻²]
rad/s²

Relation b/w S, r and θ : $\theta = S/r$ (rad) 
 $(\omega) = \theta/t \rightarrow \omega = 2\pi f$ $\omega = \text{rpm}/60 \times 2\pi$ $\omega = \text{rph}/3600 \times 2\pi$

Average angular velocity: $\vec{\omega}_{av} = \Delta\vec{\theta}/\Delta t$ **Instantaneous angular velocity:** $\vec{\omega} = \lim_{\Delta t \rightarrow 0} \Delta\vec{\theta}/\Delta t$

Average angular acceleration: $\vec{\alpha}_{av} = \Delta\vec{\omega}/\Delta t$ **Instantaneous angular acceleration:** $\vec{\alpha}_{ins} = \lim_{\Delta t \rightarrow 0} \frac{\Delta\vec{\omega}}{\Delta t}$

Equation of angular motion:
 $v = r\omega$
 $a = r\alpha$
 $\theta = \omega_i t + \frac{1}{2} \alpha t^2$ $(\omega) 2\alpha\theta = \omega_f^2 - \omega_i^2$

Moment of inertia of a thin rod of length L: $I = \frac{1}{12} mL^2$

Linear motion:

Angular motion:

Moment of inertia of hoop: $I = m r^2$

$S = vt$
 $v_f = v_i + at$
 $v_f^2 - v_i^2 = 2aS$
 $S = v_i t + \frac{1}{2} at^2$

$\theta = \omega t$
 $\omega_f = \omega_i + \alpha t$
 $\omega_f^2 - \omega_i^2 = 2\alpha\theta$
 $\theta = \omega_i t + \frac{1}{2} \alpha t^2$

Moment of inertia of a disc: $I = \frac{1}{2} m r^2$
Moment of inertia of sphere: $I = \frac{2}{5} m r^2$

Centrifugal force is not a real vector.
 $F = ma$
 $P = mv$
 $K.E_{lin} = \frac{1}{2} m v^2$

Moment of inertia:
 $I = m r^2$
 $T = I\alpha$
 $L = I\omega$
 $K.E_{rot} = \frac{1}{2} I \omega^2$

Critical orbital velocity:
 $v = \sqrt{2gR}$ $v = \sqrt{\frac{GM}{R}}$
Time period of close orbiting satellite: $T = 2\pi R/v$

Apparent weight

Rotational K.E $\rightarrow K.E_{rot} = \frac{1}{2} I \omega^2$

Rest: $T = mg$ *
Moving up: $T = mg + ma$ *
Moving down: $T = mg - ma$ *
Freely fall: $T = 0$ *

Velocity of disc: $\rightarrow v = \sqrt{\frac{4}{3} gh}$
" " " sphere: $\rightarrow v = \sqrt{\frac{10}{7} gh}$
" " " hoop: $\rightarrow v = \sqrt{gh}$

Orbital velocity: $v = \sqrt{\frac{GM}{R}}$
Spinning frequency of a satellite:
 $f = \frac{1}{2\pi} \sqrt{g/R}$

SI unit of angular momentum: Js. ($\text{kg m}^2 \text{s}^{-1}$)
 3 satellites form LPS in geostationary orbit.

Orbital radius of geostationary satellite: $r = \left(\frac{g_m T^2}{4\pi^2} \right)^{1/3}$
 $K.E_{total} = K.E_{trans} + K.E_{rot}$

Critical velocity to put an satellite in an orbit close to earth:

Centripetal acceleration:
 $a_c = v^2/r$
 $a_c = v\omega$
 $a_c = r\omega^2$
Centripetal force:
 $F_c = \frac{mv^2}{r}$
 $F_c = m r \omega^2$
Angular momentum measure.

Banking of road:
 $v = \sqrt{rg \tan \theta}$
Moment of inertia (I = m r^2)
 SI unit kg m^2
 Dimension $[ML^2]$

Angular momentum and torque:

$\vec{\Delta L} = \vec{r} \times \vec{\Delta P}$
 Divide both sides by Δt
 $\frac{\Delta \vec{L}}{\Delta t} = \vec{r} \times \frac{\Delta \vec{P}}{\Delta t}$
 $\vec{\tau} = \vec{r} \times \vec{F}$
 $\vec{\tau} = \Delta \vec{L} / \Delta t$

Law of conservation of angular momentum:
 $\tau = 0$
 $\frac{\Delta L}{\Delta t} = 0$
 $\Delta L = 0$
 $L_2 - L_1 = 0$
 $L_2 = L_1$
 $L = \text{constant}$

is 7.9 km/s